
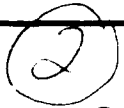
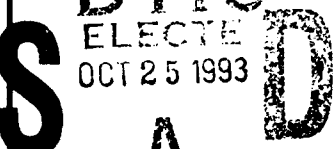




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Wave Techniques for Noise Modeling and Measurement

**Scott W. Wedge
David B. Rutledge**

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Wave Techniques for Noise Modeling and Measurement

Scott W. Wedge, *Member, IEEE*, and David B. Rutledge, *Senior Member, IEEE*

Abstract—The noise wave approach is applied to analysis, modeling, and measurement applications. Methods are presented for the calculation of component and network noise wave correlation matrices. Embedding calculations, relations to two-port figures-of-merit, and transformations to traditional representations are discussed. Simple expressions are derived for MESFET and HEMT noise wave parameters based on a linear equivalent circuit. A noise wave measurement technique is presented and experimentally compared with the conventional method.

I. INTRODUCTION

CIRCUIT theory provides numerous alternatives for the characterization of noise in linear networks. Hartmann [1] alone presented twelve representations for the simple two-port. Noise is typically characterized using combinations of equivalent voltage and current sources. For high frequency circuit applications, however, a wave interpretation of noise has advantages. Noise waves have received a moderate amount of interest since their introduction by Penfield [2]. Bosma [3] used noise waves to solve the Haus and Adler [4] optimum noise performance problem. Hecken [5] used them to simplify noise performance calculations through signal-flow graph theory. Kanaglekar *et al.* [6] and Dobrowolski [7], [8] have presented CAD algorithms strictly in terms of noise waves and scattering parameters.

In the noise wave representation, a circuit element's noise is described using waves that emanate from its ports. A linear two-port represented by noise waves and scattering parameters is shown schematically in Fig. 1. Noise waves c_1 and c_2 contribute to the scattered waves such that the wave variables and scattering parameters satisfy

$$\begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = \begin{pmatrix} s_{11} & s_{12} \\ s_{21} & s_{22} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} + \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}. \quad (1)$$

The noise waves are time-varying complex random variables characterized by a correlation matrix C_s given by

$$C_s = \begin{pmatrix} \overline{|c_1|^2} & \overline{c_1 c_2^*} \\ \overline{c_2 c_1^*} & \overline{|c_2|^2} \end{pmatrix} \quad (2)$$

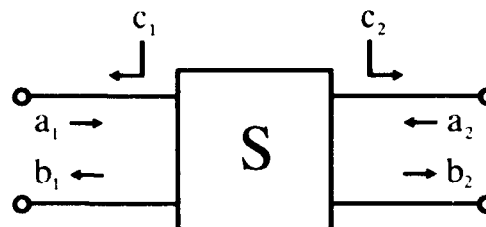


Fig. 1 The schematic representation of a two-port circuit element using scattering parameters and noise waves

where the overbar indicates time averaging with an implicit assumption of ergodicity and jointly wide-sense stationary processes. The diagonal terms of C_s give the noise power deliverable to the terminations in a 1-Hz bandwidth. The off-diagonal terms are correlation products. The noise wave correlation matrix C_s is Hermitian and its components are referred to as noise wave parameters.

The strength of the noise wave representation lies in a compatibility with distributed circuit variables that permits noise analysis problems to be formalized and solved using scattering parameters. Simple relations can often be found between a circuit element's scattering and noise wave parameters. The availability of accurate scattering parameter measurements then contributes to the accuracy of the noise analysis. Noise wave parameters are numerically stable. The reflections and resonances common in microwave circuits may cause voltage and current quantities to vary dramatically, while the limited range of noise wave quantities makes them ideal for CAD applications. The wave interpretation of noise has also led to alternative noise parameter measurement methods [9], [10].

In this paper new applications of the noise wave representation in analysis, modeling, and measurement are presented. Section II presents noise wave analysis techniques. Noise calculations for interconnected multiport networks and two-port figures-of-merit are discussed. In Section III, equivalent circuits are used to derive simple expressions for the noise wave parameters of the MESFET and HEMT. The modeling approach taken is compared with experiment. Section IV describes a new method for making direct measurement of noise wave parameters. The method is simpler than conventional methods that use source-pull tuners to extract T_{min} , Γ_{opt} , and R_n . The noise wave and conventional measurement techniques are compared experimentally.

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II. NOISE WAVE NETWORK ANALYSIS

Analyzing a network for its noise properties involves its division into the smallest number of uncorrelated components. The signal and noise correlation matrices for the components are used to solve for those of the overall network. In general, the network and its components are multiport elements. In the noise wave representation each multiport element has scattering matrix S , incident and output wave vectors (a and b , respectively), and noise wave vector c satisfying

$$b = Sa + c. \quad (3)$$

The multiport noise wave correlation matrix C_c of each element is given by

$$C_c = \overline{cc^\dagger} \quad (4)$$

where the dagger indicates the Hermitian conjugate, and the overbar the time averaged correlation product. At a given frequency the signal and noise properties of a linear n -port device are completely characterized by $n \times n$ scattering and noise wave correlation matrices. In Fig. 2, this approach is compared to the more traditional multiport admittance and impedance representations. Included in the comparison are circuit diagrams and matrix relations for voltage, current, and wave quantities. The use of multiple noise representations can sometimes lead to more efficient analyses [11]; transformations can be used to avoid a non-existent representation, to simplify calculations, or to avoid singularities. The family of transformations between wave, impedance, and admittance representations is included in Fig. 2. Admittance and impedance matrices are assumed normalized.

A. Embedded Multiport Networks

Any linear noise analysis problem can be solved through one or more applications of the embedded network problem illustrated in Fig. 3. A noisy multiport subnetwork with scattering matrix S is shown embedded in a noisy subnetwork with scattering matrix T . The two subnetworks have known noise wave correlation matrices C_s and C_t , respectively. The scattering and noise wave correlation matrices, S_{net} and C_{net} , for the aggregate network are found by partitioning the embedding network's scattering matrix T into submatrices that satisfy

$$\begin{pmatrix} b_e \\ b_i \end{pmatrix} = \begin{pmatrix} T_{ee} & T_{ei} \\ T_{ie} & T_{ii} \end{pmatrix} \begin{pmatrix} a_e \\ a_i \end{pmatrix} + \begin{pmatrix} c_e \\ c_i \end{pmatrix} \quad (5)$$

where subscript i designates waves shared at the internal connections between networks S and T , and subscript e designates the external waves at the S_{net} terminals. The noise wave correlation matrix of network T is similarly partitioned such that

$$C_t = \begin{pmatrix} \overline{c_e c_e^\dagger} & \overline{c_e c_i^\dagger} \\ \overline{c_i c_e^\dagger} & \overline{c_i c_i^\dagger} \end{pmatrix}. \quad (6)$$

The resulting noise wave correlation matrix is then given

Representation	Admittance	Impedance	Wave
Circuit Diagram			
General Equations	$V = YI + V_s$	$V = ZI + V_s$	$b = Sa + c$
Correlation Equations	$C_v = Y C_i Y^\dagger$	$C_v = Z C_i Z^\dagger$	$C_c = S^\dagger C_i S$
Matrix Transformations	$Y = Z^{-1}$	$Z = Y^{-1}$	$S = Z^{-1}(I - Z^{-1})$
Correlation Matrix Transformations	$C_i = Y C_v Y^\dagger$	$C_i = Z C_v Z^\dagger$	$C_i = (I - S) C_c (I - S)^\dagger$

Fig. 2 A summary of the signal and noise representations and transformations for admittance, impedance, and wave parameters. The admittance matrix Y and impedance matrix Z are assumed to be normalized, and I is the identity matrix.

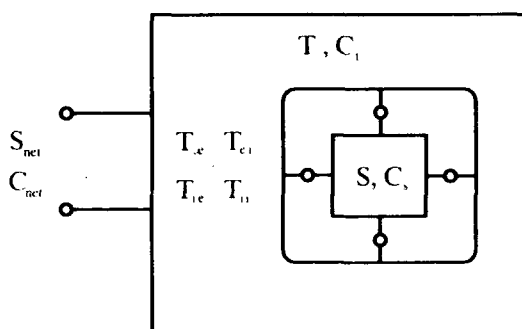


Fig. 3 A multiport network S with noise wave correlation matrix C_s embedded within network T with correlation matrix C_t . The result of the embedding is scattering and correlation matrices S_{net} and C_{net} . Network T is partitioned in the manner shown, where subscript e denotes reference to an external wave, and i denotes reference to an internal wave. Internal waves are defined as those shared at the connections between S and T .

by [3]

$$C_{net} = \Lambda C_s \Lambda^\dagger + [I] \Lambda S [I] C_t [I] \Lambda S^\dagger \quad (7)$$

where the pipe symbol ($|$) designates matrix augmentation, I is the identity matrix, and Λ is the matrix given by

$$\Lambda = T_{ei}(I - ST_{ii})^{-1}. \quad (8)$$

The network's scattering matrix is given by the well known expression [12]

$$S_{net} = T_{ee} + \Lambda ST_{ie}. \quad (9)$$

It is significant to note that matrix product ΛS is common to both the S_{net} and C_{net} expressions. During analysis, the majority of computation time is spent on the matrix inversion required for Λ , and for the calculation of this product. The penalty in combining a noise analysis with a deterministic analysis is therefore minimal. Since any network may be interpreted as a combination of embeddings, connection formulas (7) and (9) may be used as the basis for computer-aided analysis. Indeed, this approach is the wave equivalent of the admittance matrix CAD approach presented by Rizzoli and Lipparini [13].

B. Two-Port Analysis

Noise performance figures-of-merit are calculated from the signal and noise correlation matrices that result from a two-port network analysis. As with scattering parameters, noise waves are defined with respect to a normalizing impedance. This leads to simple expressions for amplifier noise performance when a zero source reflection coefficient ($\Gamma_s = 0$) is assumed. In terms of the scattering and noise wave parameters presented in (1) and (2), noise temperature T_n is given by

$$kT_n = \frac{\overline{C_1^2}}{S_{21}^2} \quad (10)$$

where k is Boltzmann's constant. Noise measure M is written

$$kT_0 M = \frac{\overline{C_1^2}}{[S_{21}]^2 + [S_{22}]^2 - 1} \quad (11)$$

where T_0 is standard temperature (290 K). A 1-Hz bandwidth is assumed in both expressions. Noise performance contours are generated by examining the variation of T_n and M with respect to non-zero Γ_s values. In terms of the two-port scattering and noise wave correlation matrices, the noise temperature function is

$$kT_n = \frac{\alpha C_s \alpha^*}{(1 - |\Gamma_s|^2)} \quad (12)$$

where α is the 1×2 row matrix

$$\alpha = \left(\Gamma_s, \frac{1 - \Gamma_s S_{11}}{S_{21}} \right) \quad (13)$$

and C_s is the matrix given in (2). Noise measure may be written

$$kT_0 M = \frac{-\alpha C_s \alpha^*}{\alpha (I - SS^*) \alpha^*} \quad (14)$$

where S is the scattering matrix of the two-port. As before, the expressions for T_n and M assume a 1-Hz bandwidth. The standard noise parameters Γ_{opt} , T_{min} , and R_n may also be written in terms of the components of C_s . Equations for the conversion between these parameter sets are given in the Appendix.

III. COMPONENT MODELING

Prior to noise wave analysis, each component of a network must be represented by a scattering and noise wave correlation matrix. The extraction of scattering parameters is well understood, and noise wave correlation matrices may often be expressed in terms of these values. For the passive multiport with thermal noise, the noise wave correlation matrix is derived directly from the scattering matrix [14]

$$C_s = kT(I - SS^*) \quad (15)$$

where k is Boltzmann's constant and T is the physical temperature. Combining this expression with (12) reveals

the noise temperature of a passive two-port in terms of its scattering matrix:

$$T_n = T \frac{\alpha (I - SS^*) \alpha^*}{(1 - |\Gamma_s|^2)} \quad (16)$$

Expressions comparable to (15) and (16) can be derived for active devices. Signal and noise modeling of the MES-FET and HEMT are based on small-signal equivalent circuits and additional frequency-independent quantities proportional to noise correlation matrix values [15]–[20]. Pospieszalski [21] has shown that the frequency-independent quantities are tantamount to resistors in the equivalent circuit possessing effective temperatures. In the simplified intrinsic equivalent circuit of Fig. 4, the gate-source resistance R_{gs} and drain-source resistance R_{ds} are assigned equivalent temperatures T_g and T_d , respectively. With the source grounded, noise wave c_1 emanates from the gate and c_2 from the drain. The value of $\overline{C_1^2}$ is due only to the temperature of input resistance R_{gs} and is given by

$$\overline{C_1^2} = kT_g(1 - |S_{11}|^2). \quad (17)$$

Noise produced by R_{gs} induces a voltage across C_{gs} that is transferred to the drain via transconductance g_m . The result is the noise correlation term

$$\overline{C_2 C_1^*} = \frac{S_{21}}{S_{11} - 1} \overline{C_1^2}. \quad (18)$$

The output noise wave c_2 results from correlated noise from the gate, and noise generated by output resistance R_{ds} at equivalent temperature T_d . It is given by

$$\overline{C_2^2} = \frac{|S_{21}|^2}{|1 - S_{11}|^2} \overline{C_1^2} + kT_d(1 - |S_{22}|^2). \quad (19)$$

Expressions for the scattering and noise wave parameters in terms of the equivalent circuit values of Fig. 4 are given in the Appendix.

Accurate device signal and noise modeling generally requires a more detailed equivalent circuit than that of Fig. 4; stray capacitance, lead resistance and inductance must be added. The effects of additional elements on the scattering and correlation matrices are computed by applying embedding calculations (5)–(9); the equivalent circuit of Fig. 4 is considered embedded in a subcircuit consisting of the additional elements. The embedding circuit is typically passive with correlation matrix found from (15). A required intermediate step is a two-port to three-port conversion of C_s . This is achieved by recognizing that the elements of an indefinite N -port noise wave correlation matrix satisfy

$$\sum_{j=1}^N \overline{C_j C_k^*} = \sum_{k=1}^N \overline{C_j C_k^*} = 0 \quad (20)$$

as do the elements of an indefinite noise current correlation matrix.

This noise analysis procedure has been applied to the Fujitsu FSX02X MESFET and FHR02X HEMT using the

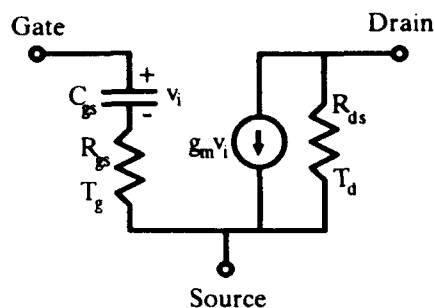


Fig. 4. Intrinsic equivalent circuit for MESFET and HEMT transistors. Gate temperature T_g is the equivalent temperature of R_g . Drain temperature T_d is the equivalent temperature of R_d . The noise voltage generated by R_g appears at v_i , resulting in correlation between input and output.

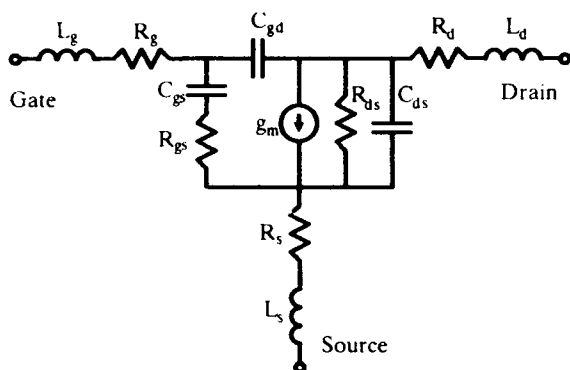


Fig. 5. A more accurate equivalent circuit for the chip form MESFET and HEMT. During noise analysis, the parasitic resistances R_g , R_s , and R_d are assumed to be at standard temperature.

TABLE I
COMPONENT VALUES FOR ELEMENTS IN THE
EQUIVALENT CIRCUIT OF FIG. 5 USED TO MODEL THE
FUJITSU FSX02X MESFET AND FHR02X HEMT

Parameter	FSX02X	FHR02X
g_m (mS)	42.5	55
τ (psec)	2.0	0.85
C_{gs} (pF)	0.33	0.2
C_{gd} (pF)	0.033	0.025
C_{ds} (pF)	0.115	0.049
R_{gs} (Ω)	3.5	2.5
R_{ds} (Ω)	270.0	188.7
R_g (Ω)	0.3	1.3
R_s (Ω)	1.8	1.3
R_d (Ω)	3.0	1.3
L_g (nH)	0.12	0.1
L_s (nH)	0.05	0.08
L_d (nH)	0.12	0.1
T_g (K)	290	290
T_d (K)	1375	1100

The transconductance g_m has an associated transit time τ such that $g_m = g_{m0} e^{-j\omega\tau}$. Gate temperature T_g is the equivalent temperature of R_g . Drain temperature T_d is the equivalent temperature of R_d . Values for both devices are for $I_{ds} = 10$ mA. The FSX02X values correspond to a bias voltage $V_{ds} = 3$ V, while $V_{ds} = 2$ V for the FHR02X.

equivalent circuit of Fig. 5. Parameter values for the equivalent circuit are listed in Table I. The results have been converted to standard noise parameters (using the

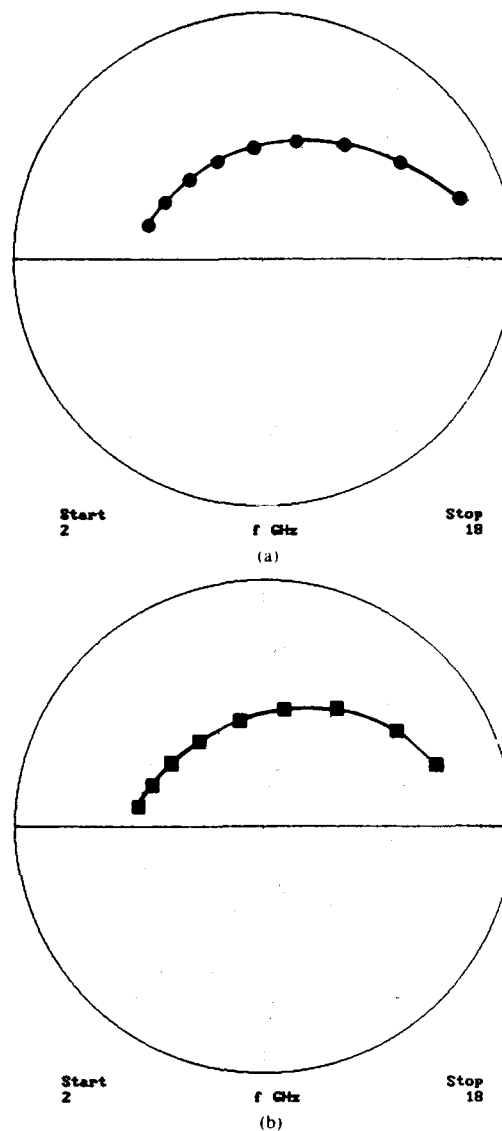


Fig. 6. Smith chart comparison of theory (a) and measurement (b) of optimum reflection coefficient Γ_{opt} for the Fujitsu FSX02X MESFET. The theoretical plot was made with $T_d = 1375$ K. Plots are from 2-18 GHz, running counterclockwise over frequency, with points shown in 2 GHz increments.

equations found in the Appendix) for a comparison with measured data provided by the manufacturer. Given in Fig. 6 are Smith chart plots of theory and measurement for Γ_{opt} for the Fujitsu FSX02X MESFET from 2-18 GHz. The theoretical plot assumes a standard gate temperature $T_g = 290$ K, suggesting that this noise is thermal in nature. A large drain temperature value ($T_d = 1375$ K) is needed to represent all noise processes in the drain-source region. Theory and measurement for the noise figure minimum F_{min} and noise resistance R_n are given in Fig. 7. Noise figure minimum and Γ_{opt} predictions are quite good. Noise resistance is slightly underestimated. Better R_n and F_{min} matching is possible by adding a pole to the fre-

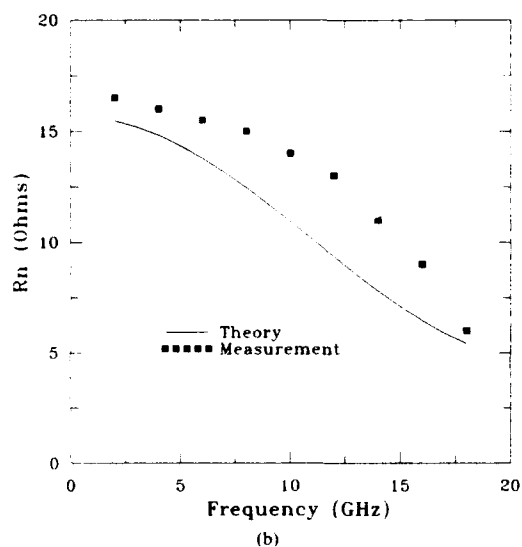
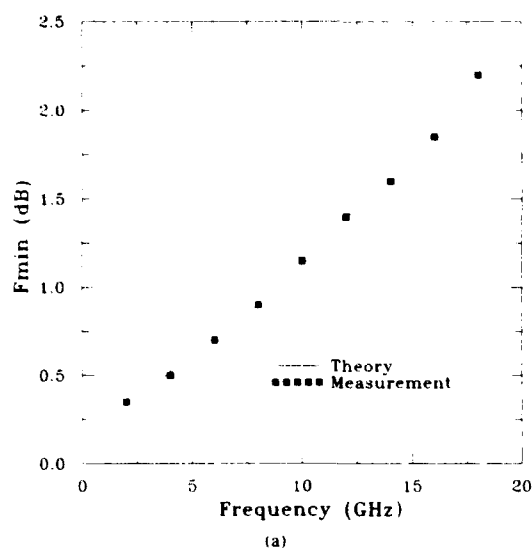


Fig. 7. Comparison of theory and measurement of noise figure minimum F_{min} (a) and noise resistance R_n (b) for the Fujitsu FSX02X MESFET. The theoretical plot was made with $T_d = 1375$ K.

quency behavior of g_m . Low frequency F_{min} predictions can be expected to deviate with measurements as $|\Gamma_{opt}|$ approaches unity. Shown in Fig. 8 are Smith chart plots of modeled and measured Γ_{opt} for the Fujitsu FHR02X HEMT from 2–26 GHz. Standard temperature is again used for the gate. Graphs showing comparisons of F_{min} and R_n are shown in Fig. 9. As before, predictions are good with the exception of R_n which deviates from theory at lower frequencies.

These examples demonstrate surprisingly good room temperature MESFET and HEMT noise modeling with a single parameter: drain temperature T_d . All other elements of the equivalent circuit (derived from scattering parameter measurements) were assumed to be at standard temperature. The limitations of this approach include de-

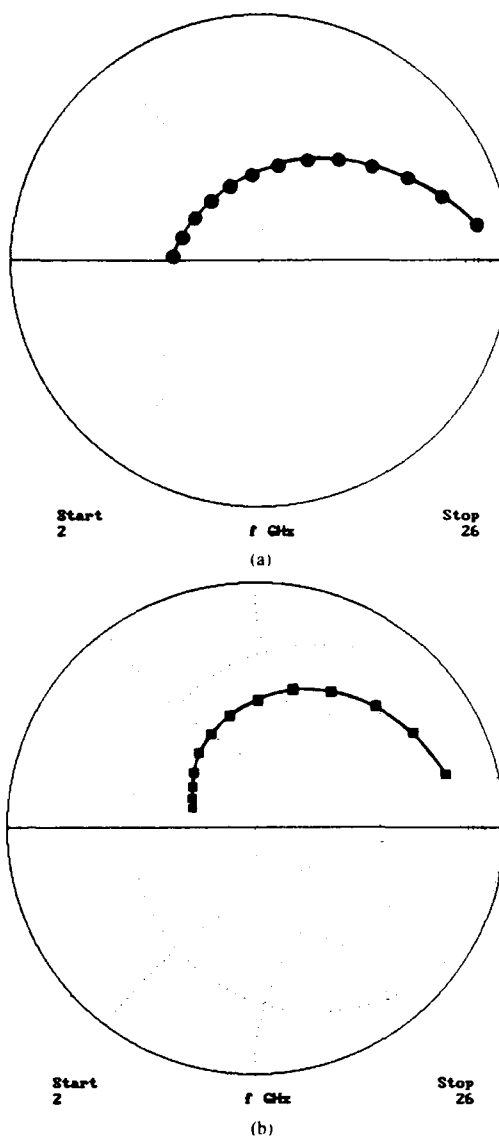


Fig. 8. Smith chart comparison of theory (a) and measurement (b) of optimum reflection coefficient Γ_{opt} for the Fujitsu FHR02X HEMT. The theoretical plot was made with $T_d = 1100$ K. Plots are from 2–26 GHz, running counterclockwise over frequency, with points shown in 2 GHz increments.

pendence on the accuracy of the equivalent circuit and the lack of low frequency noise. Yet, it is possible to express T_d as a function of frequency and bias conditions for broadband bias dependent noise modeling. The noise wave approach simplifies active and passive device modeling by using scattering parameters and these physical or equivalent temperature values.

IV. NOISE WAVE MEASUREMENTS

To measure the standard two-port noise parameters T_{min} , Γ_{opt} , and R_n , a source-pull tuner is used to present various Γ_s values to the device under test (DUT). The tuner complicates the measurement process. It may pos-

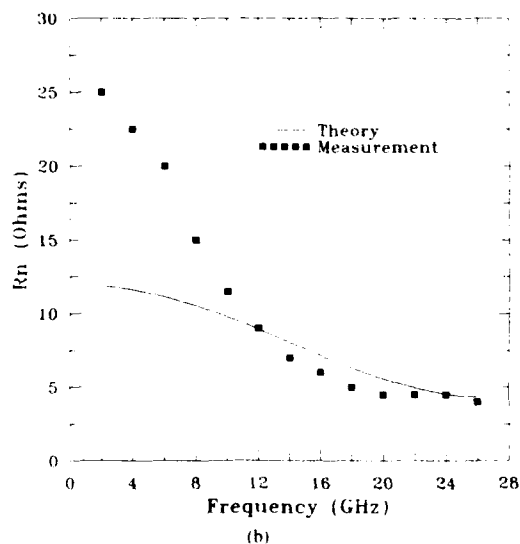
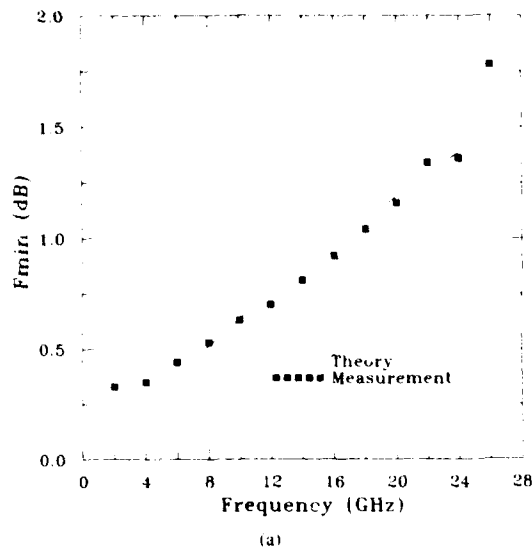


Fig. 9. Comparison of theory and measurement of noise figure minimum F_{min} (a) and noise resistance R_n (b) for the Fujitsu FHR02X HEMT. The theoretical plot was made with $T_d = 1100$ K.

sess repeatability error, have restricted tuning and frequency ranges, require frequent calibration, or cause low frequency oscillations in microwave transistors [19]. Direct measurement of the noise wave parameters ($|c_1|^2$, $c_1 c_2^*$, and $|c_2|^2$) is a simpler process due to their definition with respect to a normalizing impedance.

The apparatus represented schematically in Fig. 10 has been used to measure noise wave parameters. The DUT is shown with scattering matrix S and emanating noise waves c_1 and c_2 . At each port of the device, a circulator injects noise from a noise source into the device while terminating noise power that originates in the remainder of the system. Noise waves c_1 and c_2 emanate from the network and combine with scattered noise from the

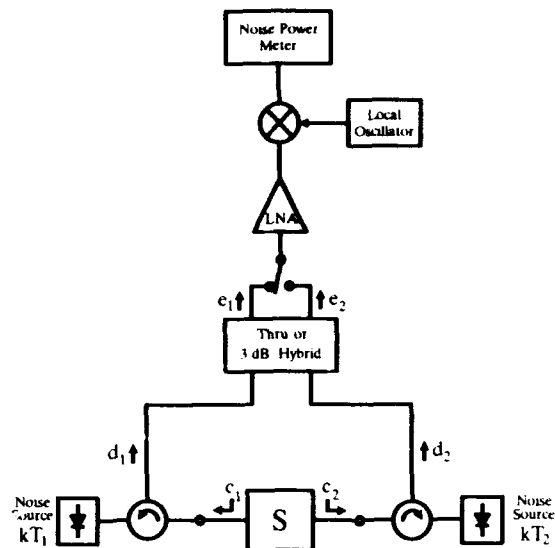


Fig. 10. Apparatus for the measurement of two-port noise wave parameters $|c_1|^2$, $|c_2|^2$, and $c_1 c_2^*$. Noise waves c_1 and c_2 emanate from network S and combine with scattered waves from the noise sources to form waves d_1 and d_2 . The noise sources have equivalent temperatures T_1 and T_2 , each capable of taking on hot and cold values. At the center is placed either a "Thru" circuit or 3 dB hybrid. The "Thru" circuit is such that $d_1 = c_1$ and $d_2 = c_2$ and permits direct measurement of $|c_1|^2$ and $|c_2|^2$. Substitution of a $0^\circ/180^\circ$ hybrid allows measurement of $\text{Re}(c_1 c_2^*)$, while a 90° hybrid allows measurement of $\text{Im}(c_1 c_2^*)$. The switch shown is assumed to be non-reflective. Noise power measurements are made at an intermediate frequency using an HP 8970 in noise power density mode.

sources to produce noise waves d_1 and d_2 given by

$$d_1 = c_1 + \sqrt{kT_1} s_{11} + \sqrt{kT_2} s_{12} \quad (21)$$

$$d_2 = c_2 + \sqrt{kT_1} s_{21} + \sqrt{kT_2} s_{22} \quad (22)$$

Power from the noise sources is written here in terms of effective temperatures T_1 and T_2 , each capable of taking on known hot or cold values. Waves d_1 and d_2 will have measurable quantities

$$\overline{|d_1|^2} = \overline{|c_1|^2} + kT_1 |s_{11}|^2 + kT_2 |s_{12}|^2 \quad (23)$$

$$\overline{|d_2|^2} = \overline{|c_2|^2} + kT_1 |s_{21}|^2 + kT_2 |s_{22}|^2 \quad (24)$$

$$\overline{d_1 d_2^*} = \overline{c_1 c_2^*} + kT_1 s_{11} s_{21}^* + kT_2 s_{12} s_{22}^* \quad (25)$$

The apparatus of Fig. 10 allows each of the above unknown right-hand-side values to be obtained through a set of noise power measurements. First, a "Thru" circuit is inserted at the center of the apparatus such that $d_1 = c_1$ and $d_2 = c_2$. Four noise power measurements are made of $\overline{|d_1|^2}$ and $\overline{|d_2|^2}$ using hot and cold values for both T_1 and T_2 . Using (23) and (24), this measurement data is sufficient to solve for the six unknowns $|c_1|^2$, $|c_2|^2$, $|s_{11}|^2$, $|s_{12}|^2$, $|s_{21}|^2$, and $|s_{22}|^2$. Measurement of noise wave correlation can be accomplished with 3 dB hybrid couplers [14]. With a lossless $0^\circ/180^\circ$ 3 dB hybrid inserted such

that

$$e_1 = \frac{1}{\sqrt{2}} (d_1 + d_2) \quad (26)$$

$$e_2 = \frac{1}{\sqrt{2}} (d_1 - d_2) \quad (27)$$

the measured noise powers are given by

$$|e_1|^2 = \frac{1}{2} (|d_1|^2 + |d_2|^2 + 2\text{Re}(d_1 d_2^*)) \quad (28)$$

$$|e_2|^2 = \frac{1}{2} (|d_1|^2 + |d_2|^2 - 2\text{Re}(d_1 d_2^*)) \quad (29)$$

The difference in these values yields

$$\begin{aligned} |e_1|^2 - |e_2|^2 &= 2 \text{Re}(d_1 d_2^*) \\ &= 2 [\text{Re}(c_1 c_2^*) + kT_1 \text{Re}(s_{11} s_{21}^*) \\ &\quad + kT_2 \text{Re}(s_{12} s_{22}^*)] \end{aligned} \quad (30)$$

where the values for $|e_1|^2$ and $|e_2|^2$ have been compared assuming consistent values of T_1 and T_2 . The set of measurements taken at hot and cold values for T_1 and T_2 now results in solutions for unknowns $\text{Re}(c_1 c_2^*)$, $\text{Re}(s_{11} s_{21}^*)$, and $\text{Re}(s_{12} s_{22}^*)$. When the $0^\circ/180^\circ$ hybrid is replaced with a 90° 3 dB hybrid, the difference in noise powers becomes

$$\begin{aligned} |e_1|^2 - |e_2|^2 &= 2 \text{Im}(d_1 d_2^*) \\ &= 2 [\text{Im}(c_1 c_2^*) + kT_1 \text{Im}(s_{11} s_{21}^*) \\ &\quad + kT_2 \text{Im}(s_{12} s_{22}^*)] \end{aligned} \quad (31)$$

and an additional set of measurements now permits solution of the imaginary components $\text{Im}(c_1 c_2^*)$, $\text{Im}(s_{11} s_{21}^*)$, and $\text{Im}(s_{12} s_{22}^*)$.

This system has been constructed and a series of measurements performed at 4 GHz on a MESFET amplifier over a range of bias currents. An HP 8970 noise figure meter (in power density mode) was used to measure noise power. A simple short-open-thru calibration procedure was followed to compensate for losses and noise in the apparatus. For experimental comparison, measurements were made at the same bias points using the conventional source-pull tuner technique. A mechanical slide-screw tuner was used and the additional measurements and corrections recommended by Strid [22] were performed. The results, in terms of standard noise parameters, are compared in Fig. 11. The similarities are surprising considering the dramatic differences in the measurement methods and their sources of error: the tuner method has errors due to tuner repeatability, unstable bias, and noise figure measurement uncertainty; wave method errors are due to uncertainty in temperatures T_1 and T_2 and a simplified calibration procedure (the directional couplers were assumed to have ideal phase shifts).

The *wave method* of noise parameter measurement has several advantages. It uses many off-the-shelf compo-

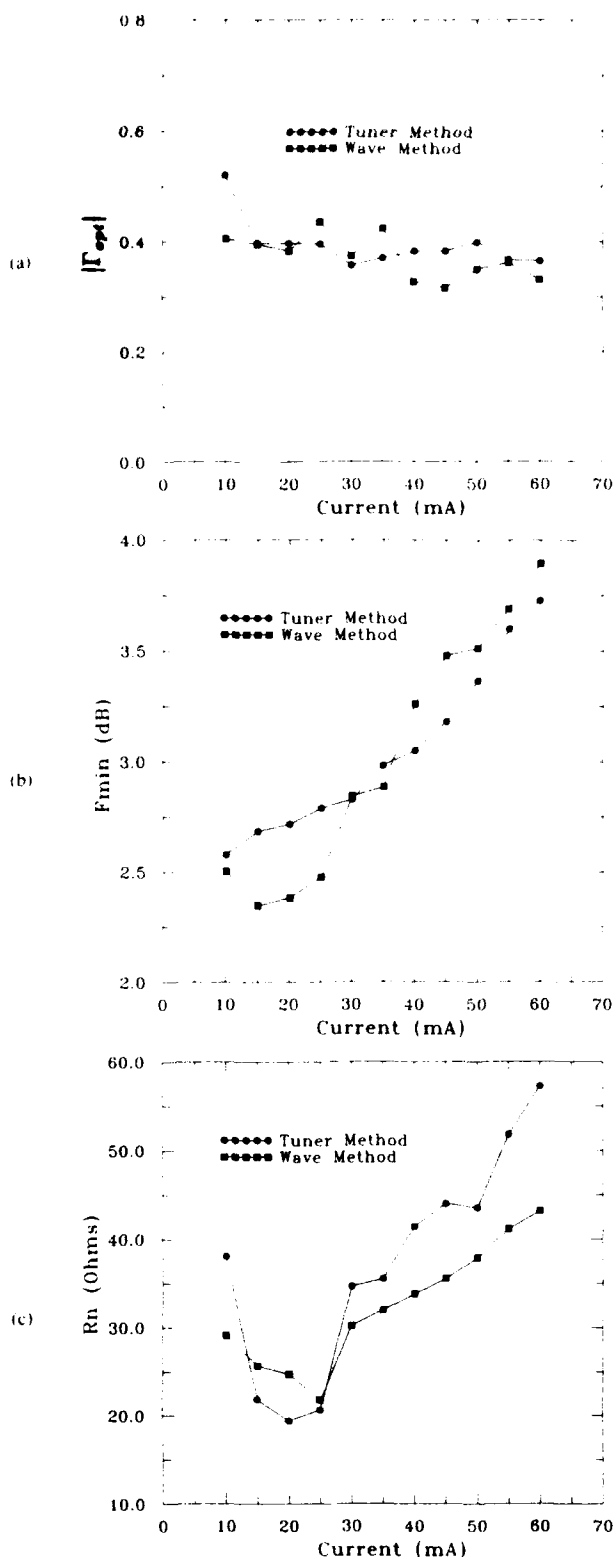


Fig. 11. Comparison of the tuner and wave measurement methods in determining the optimum reflection coefficient Γ_{opt} (a), the noise figure minimum F_{min} (b), and the noise resistance R_n (c) of an amplifier based on single Fujitsu FSC10 MESFET. The measurements were performed at 4 GHz with amplifier bias current varied from 10–60 mA.

nents, may be configured for operation at RF through millimeter-wave frequencies, and requires no source-pull tuner. In addition to the noise wave parameters, the magnitudes of the scattering parameters, and the complex scattering parameter products $s_{11}s_{21}^*$ and $s_{11}^*s_{21}$ are determined. The system of equations that is manipulated is over-determined, and lends itself to statistical analysis. Noise contributions from the measurement apparatus are predicted by embedding equation (7), and may be removed by a calibration procedure. Many other configurations of the measurement apparatus of Fig. 10 are possible. Withington [10], for example, has presented a similar system that uses interferometric measurements. Measurement accuracy and bandwidth may be improved by using two LNA's and mixers. The directional coupler substitutions described here are avoided by using the six-port network described by Engen [23] as a single correlation network [24].

IV. CONCLUSIONS

The noise wave representation offers alternative analysis, modeling and measurement techniques. Noise wave analysis may be performed solely in terms of distributed circuit variables. Derivation of noise wave parameters for many microwave components is a straightforward process, requiring only scattering parameters and physical or effective temperatures. The wave approach to noise parameter measurement offers advantages over conventional methods. It requires no source-pull tuner, uses off-the-shelf components, and is promising for millimeter-wave applications.

APPENDIX

Noise wave parameters for active devices may be derived from the standard noise parameters or calculated from equivalent circuit values. In terms of T_{\min} , Γ_{opt} , and R_n the noise wave parameters are

$$\overline{c_1^2} = kT_{\min}(|s_{11}|^2 + 1) + \frac{kt(1 + |s_{11}|^2)\Gamma_{\text{opt}}^2}{1 + |\Gamma_{\text{opt}}|^2} \quad (32)$$

$$\overline{c_2^2} = |s_{21}|^2 \left(kT_{\min} + \frac{kt|\Gamma_{\text{opt}}|^2}{1 + |\Gamma_{\text{opt}}|^2} \right) \quad (33)$$

$$\overline{c_1 c_2^*} = \frac{-s_{21}^* \Gamma_{\text{opt}}^* kt}{1 + |\Gamma_{\text{opt}}|^2} + \frac{s_{11}}{s_{21}} \overline{c_2^2} \quad (34)$$

where kt is the normalized temperature-energy given by

$$kt = \frac{4kT_0 R_n}{Z_0} \quad (35)$$

and Z_0 is the normalization impedance. The inverse relations are

$$kt = \left[c_1 - c_2 \left(\frac{1 + |s_{11}|^2}{|s_{21}|} \right) \right]^2 \quad (36)$$

$$kT_{\min} = \frac{|\overline{c_2^2}|^2 - |\overline{c_1 c_2^*}|^2}{|s_{21}|^2 (1 + |\Gamma_{\text{opt}}|^2)} \quad (37)$$

$$\Gamma_{\text{opt}} = \frac{\eta}{2} \begin{pmatrix} 1 & 1 & 4 \\ & \sqrt{1} & \eta \end{pmatrix} \quad (38)$$

where

$$\eta = \frac{c_1^2 + c_2^2 + c_1 c_2^* + c_1^* c_2}{c_1^2 + c_2^2 + c_1 c_2^* + c_1^* c_2} \quad (39)$$

The inverse relations have been somewhat simplified through use of the identity

$$\begin{aligned} c_1 c_2^* + c_1^* c_2 &= 2\text{Re}(c_1 c_2^*) \\ &= c_1^2 + c_2^2 - 2\text{Re}(c_1 c_2^*) + c_1^2 + c_2^2 \end{aligned} \quad (40)$$

Noise wave parameters for the intrinsic MESFET and HEMT with the equivalent circuit given by Fig. 4 may be written in terms of scattering parameters or equivalent circuit parameters. The scattering matrix of the equivalent circuit of Fig. 4 is given by

$$S = \begin{pmatrix} 1 + j\omega C_{gs}(r_{gs} + Z_0) & 0 \\ 1 + j\omega C_{gs}(r_{gs} + Z_0) & 0 \\ -2g_m r_{ds} Z_0 & r_{ds} + Z_0 \\ (r_{ds} + Z_0)[1 + j\omega C_{gs}(r_{gs} + Z_0)] & r_{ds} + Z_0 \end{pmatrix} \quad (41)$$

Solving for the noise wave parameters using (17)–(19) and assuming constant values of gate temperature T_g and drain temperature T_d gives

$$\overline{c_1^2} = \frac{4kT_g r_{gs} Z_0 \omega^2 C_{gs}^2}{1 + \omega^2 C_{gs}^2 (r_{gs} + Z_0)^2} \quad (42)$$

$$\overline{c_1 c_2^*} = \frac{-j4kT_g r_{gs} r_{ds} Z_0 g_m \omega C_{gs}}{(r_{ds} + Z_0)[1 + \omega^2 C_{gs}^2 (r_{gs} + Z_0)^2]} \quad (43)$$

$$\begin{aligned} \overline{c_2^2} &= \frac{4kT_d r_{ds} r_{gs} Z_0 g_m^2}{(r_{ds} + Z_0)[1 + \omega^2 C_{gs}^2 (r_{gs} + Z_0)^2]} \\ &+ \frac{4kT_d r_{ds} Z_0}{(r_{ds} + Z_0)^2} \end{aligned} \quad (44)$$

These parameters are well behaved down to $\omega = 0$, but low-frequency noise effects are not included. Frequency dependent expressions for T_g and T_d may be used to include these effects.

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